

# 誤差逆伝播法の応用

2017年6月9日



# 今回の内容

- 誤差逆伝播法応用。
- 誤差逆伝播法コード解説。
- 輪読(4章)。



# class NeuralNetwork(init)

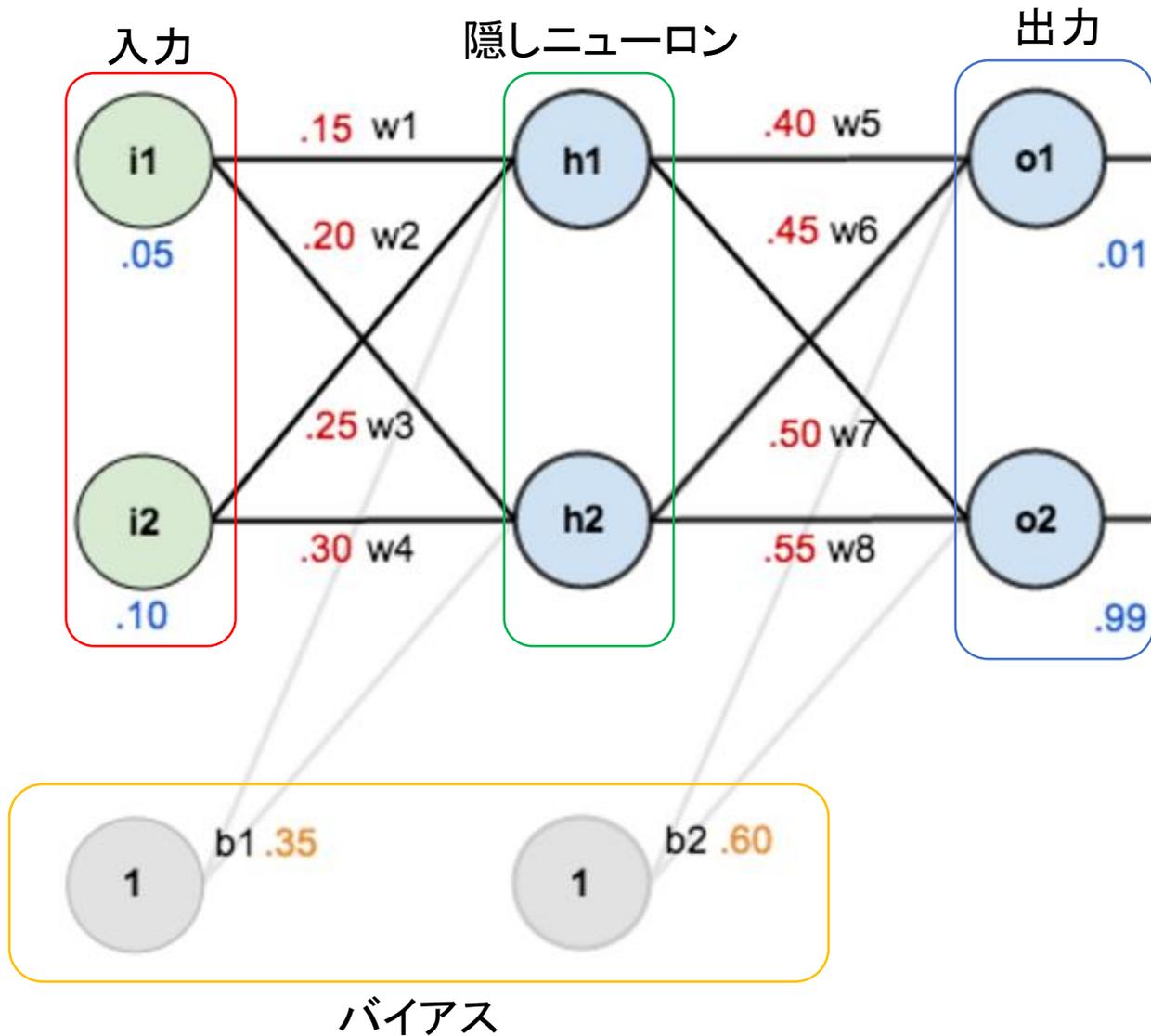
```
def __init__(self, num_inputs, num_hidden, num_outputs, hidden_layer_weights = None,
             hidden_layer_bias = None, output_layer_weights = None, output_layer_bias = None):
    self.num_inputs = num_inputs

    self.hidden_layer = NeuronLayer(num_hidden, hidden_layer_bias)
    self.output_layer = NeuronLayer(num_outputs, output_layer_bias)

    self.init_weights_from_inputs_to_hidden_layer_neurons(hidden_layer_weights)
    self.init_weights_from_hidden_layer_neurons_to_output_layer_neurons(output_layer_weights)
```

- 入力層、隠れ層、出力層のノード数(今回はどれも2)、隠れ層の重み( $w_1 \sim w_4$ )、隠れ層のバイアス( $b_1$ )、出力層の重み( $w_5 \sim w_8$ )、出力層のバイアス( $b_2$ )を受け取る。
- さらに、hidden\_layerとoutput\_layerを定義し、その中にはそれぞれに対応するノードとバイアスを入れる。層を構成する意味合い。

# class NeuralNetwork(init)のイメージ



# class NeuralNetwork(init\_weight関数)

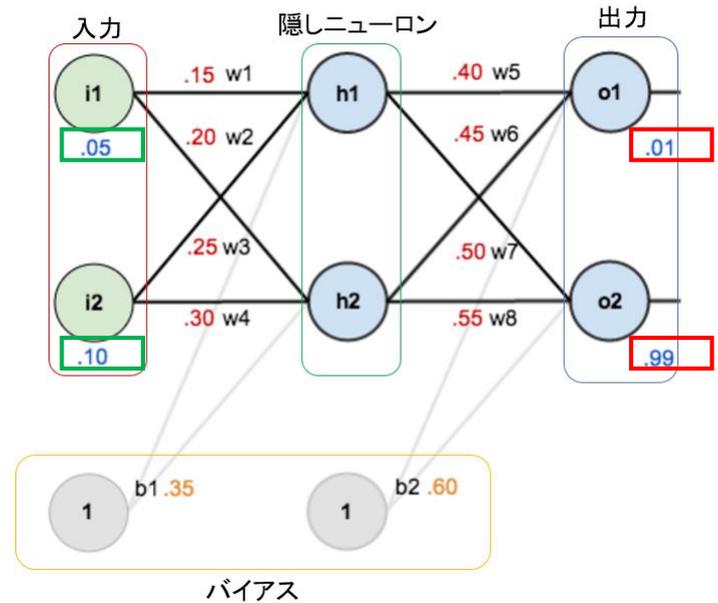
```
def init_weights_from_inputs_to_hidden_layer_neurons(self, hidden_layer_weights):
    weight_num = 0
    for h in range(len(self.hidden_layer.neurons)):
        for i in range(self.num_inputs):
            if not hidden_layer_weights:
                self.hidden_layer.neurons[h].weights.append(random.random())
            else:
                self.hidden_layer.neurons[h].weights.append(hidden_layer_weights[weight_num])
            weight_num += 1

def init_weights_from_hidden_layer_neurons_to_output_layer_neurons(self, output_layer_weights):
    weight_num = 0
    for o in range(len(self.output_layer.neurons)):
        for h in range(len(self.hidden_layer.neurons)):
            if not output_layer_weights:
                self.output_layer.neurons[o].weights.append(random.random())
            else:
                self.output_layer.neurons[o].weights.append(output_layer_weights[weight_num])
            weight_num += 1
```

- 入力層と隠れ層の間の重み( $w_1 \sim w_4$ )、隠れ層と出力層の間の重み( $w_5 \sim w_8$ )をそれぞれの関数でinitする。

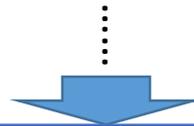
# class NeuralNetwork

```
def inspect(self):  
    print('-----')  
    print('* Inputs: {}'.format(self.num_inputs))  
    print('-----')  
    print('Hidden Layer')  
    self.hidden_layer.inspect()  
    print('-----')  
    print('* Output Layer')  
    self.output_layer.inspect()  
    print('-----')  
  
def feed_forward(self, inputs):  
    hidden_layer_outputs = self.hidden_layer.feed_forward(inputs)  
    return self.output_layer.feed_forward(hidden_layer_outputs)
```



- inspectは呼び出されていない。
- feed\_forwardは、出力層における出力(推定値)を出す。この値が、学習を重ねるごとに、目標値に近づく。

[0.7513650695523157, 0.7729284653214625]



[0.01591362044355068, 0.9840642735146238]

```
for i in range(10000):  
    nn.train([0.05, 0.1], [0.01, 0.99]) ← 入力値と目標値  
    print(i, round(nn.calculate_total_error([[0.05, 0.1], [0.01, 0.99]]), 9))
```

# class NeuralNetwork(train関数)

```
# Uses online learning, ie updating the weights after each training case
def train(self, training_inputs, training_outputs):
    self.feed_forward(training_inputs)

    # 1. Output neuron deltas
    pd_errors_wrt_output_neuron_total_net_input = [0] * len(self.output_layer.neurons)
    for o in range(len(self.output_layer.neurons)):
        #  $\partial E / \partial z_i$ 
        pd_errors_wrt_output_neuron_total_net_input[o] = self.output_layer.neurons[o].calculate_pd_error_wrt_total_net_input(training_outputs[o])

    # 2. Hidden neuron deltas
    pd_errors_wrt_hidden_neuron_total_net_input = [0] * len(self.hidden_layer.neurons)
    for h in range(len(self.hidden_layer.neurons)):
        # We need to calculate the derivative of the error with respect to the output of each hidden layer neuron
        #  $dE/dy_i = \sum \partial E / \partial z_i * \partial z_i / \partial y_i = \sum \partial E / \partial z_i * w_{ij}$ 
        d_error_wrt_hidden_neuron_output = 0
        for o in range(len(self.output_layer.neurons)):
            d_error_wrt_hidden_neuron_output += pd_errors_wrt_output_neuron_total_net_input[o] * self.output_layer.neurons[o].weights[h]

        #  $\partial E / \partial z_i = dE/dy_i * \partial z_i / \partial$ 
        pd_errors_wrt_hidden_neuron_total_net_input[h] = d_error_wrt_hidden_neuron_output * self.hidden_layer.neurons[h].calculate_pd_total_net_input_wrt_input()
```

- 重み更新の準備。
- 出力層部分と、隠れ層部分とで別の関数を使っている。
- Neuronクラスの関数を呼び出して計算しているため、ここを見ただけでは何をしているか分かりにくい。

# class NeuralNetwork(train関数)

```
# Uses online learning, ie updating the weights after each training case
def train(self, training_inputs, training_outputs):
    self.feed_forward(training_inputs)

    # 1. Output neuron deltas
    pd_errors_wrt_output_neuron_total_net_input = [0] * len(self.output_layer.neurons)
    for o in range(len(self.output_layer.neurons)):
        #  $\partial E / \partial z_i$ 
        pd_errors_wrt_output_neuron_total_net_input[o] = self.output_layer.neurons[o].calculate_pd_error_wrt_total_net_input(training_outputs[o])

    # 2. Hidden neuron deltas
    pd_errors_wrt_hidden_neuron_total_net_input = [0] * len(self.hidden_layer.neurons)
    for h in range(len(self.hidden_layer.neurons)):
        # We need to calculate the derivative of the error with respect to the output of each hidden layer neuron
        #  $dE/dy_i = \sum \partial E / \partial z_i * \partial z / \partial y_i = \sum \partial E / \partial z_i * w_{ij}$ 
        d_error_wrt_hidden_neuron_output = 0
        for o in range(len(self.output_layer.neurons)):
            d_error_wrt_hidden_neuron_output += pd_errors_wrt_output_neuron_total_net_input[o] * self.output_layer.neurons[o].weights[h]

        #  $\partial E / \partial z_i = dE/dy_i * \partial z_i / \partial$ 
        pd_errors_wrt_hidden_neuron_total_net_input[h] = d_error_wrt_hidden_neuron_output * self.hidden_layer.neurons[h].calculate_pd_total_net_input_wrt_input()
```

$$\frac{\partial E_{total}}{\partial w_5} = \frac{\partial E_{total}}{\partial out_{o1}} * \frac{\partial out_{o1}}{\partial net_{o1}} * \frac{\partial net_{o1}}{\partial w_5}$$

output

$$\frac{\partial E_{total}}{\partial w_1} = \frac{\partial E_{total}}{\partial out_{h1}} * \frac{\partial out_{h1}}{\partial net_{h1}} * \frac{\partial net_{h1}}{\partial w_1}$$

hidden

- これら上2つの式の分割部分それぞれを求める。  
一部分は今回スライドp.14、p.15にある関数に投げている。  
(neuronクラスにおける処理)

# class NeuralNetwork(train関数続き)

```
# 3. Update output neuron weights
for o in range(len(self.output_layer.neurons)):
    for w_ho in range(len(self.output_layer.neurons[o].weights)):
        #  $\partial E / \partial w_{oi} = \partial E / \partial z_i * \partial z_i / \partial w_{oi}$ 
        pd_error_wrt_weight = pd_errors_wrt_output_neuron_total_net_input[o] * self.output_layer.neurons[o].calculate_pd_total_net_input_wrt_weight(w_ho)
        #  $\Delta w = \alpha * \partial E / \partial w_i$ 
        self.output_layer.neurons[o].weights[w_ho] -= self.LEARNING_RATE * pd_error_wrt_weight
```

$$\frac{\partial E_{total}}{\partial w_5} = \frac{\partial E_{total}}{\partial out_{o1}} * \frac{\partial out_{o1}}{\partial net_{o1}} * \frac{\partial net_{o1}}{\partial w_5}$$

$$w_5^+ = w_5 - \eta * \frac{\partial E_{total}}{\partial w_5}$$

```
# 4. Update hidden neuron weights
for h in range(len(self.hidden_layer.neurons)):
    for w_ih in range(len(self.hidden_layer.neurons[h].weights)):
        #  $\partial E / \partial w_i = \partial E / \partial z_i * \partial z_i / \partial w_i$ 
        pd_error_wrt_weight = pd_errors_wrt_hidden_neuron_total_net_input[h] * self.hidden_layer.neurons[h].calculate_pd_total_net_input_wrt_weight(w_ih)
        #  $\Delta w = \alpha * \partial E / \partial w_i$ 
        self.hidden_layer.neurons[h].weights[w_ih] -= self.LEARNING_RATE * pd_error_wrt_weight
```

$$\frac{\partial E_{total}}{\partial w_1} = \frac{\partial E_{total}}{\partial out_{h1}} * \frac{\partial out_{h1}}{\partial net_{h1}} * \frac{\partial net_{h1}}{\partial w_1}$$

$$w_1^+ = w_1 - \eta * \frac{\partial E_{total}}{\partial w_1}$$

- 重みの更新に関する部分。
- 出力層部分と、隠れ層部分とで分かれている。

# class NeuralNetwork (calculate\_total\_error関数)

```
def calculate_total_error(self, training_sets):  
    total_error = 0  
    for t in range(len(training_sets)):  
        training_inputs, training_outputs = training_sets[t]  
        self.feed_forward(training_inputs)  
        for o in range(len(training_outputs)):  
            total_error += self.output_layer.neurons[o].calculate_error(training_outputs[o])  
    return total_error
```

$$E_{total} = \sum \frac{1}{2}(target - output)^2$$

- 総誤差計算。
- 前回スライドp.15を参照。また、部分ごとの誤差は今回スライドp.13に示すcalculate\_errorで行う。

# class NeuronLayer

```
class NeuronLayer:
    def __init__(self, num_neurons, bias):

        # Every neuron in a layer shares the same bias
        self.bias = bias if bias else random.random()

        self.neurons = []
        for i in range(num_neurons):
            self.neurons.append(Neuron(self.bias))

    def inspect(self):
        print('Neurons:', len(self.neurons))
        for n in range(len(self.neurons)):
            print(' Neuron', n)
            for w in range(len(self.neurons[n].weights)):
                print(' Weight:', self.neurons[n].weights[w])
            print(' Bias:', self.bias)

    def feed_forward(self, inputs):
        outputs = []
        for neuron in self.neurons:
            outputs.append(neuron.calculate_output(inputs))
        return outputs

    def get_outputs(self):
        outputs = []
        for neuron in self.neurons:
            outputs.append(neuron.output)
        return outputs
```

- 層におけるバイアスとノードの設定に関する部分。
- これらによりネットワークが形成される。

# class Neuron

```
:class Neuron:
    def __init__(self, bias):
        self.bias = bias
        self.weights = []

    def calculate_output(self, inputs):
        self.inputs = inputs
        self.output = self.squash(self.calculate_total_net_input())
        return self.output

    def calculate_total_net_input(self):
        total = 0
        for i in range(len(self.inputs)):
            total += self.inputs[i] * self.weights[i]
        return total + self.bias

    # Apply the logistic function to squash the output of the neuron
    # The result is sometimes referred to as 'net' [2] or 'net' [1]
    def squash(self, total_net_input):
        return 1 / (1 + math.exp(-total_net_input))
```

$$out_{h1} = \frac{1}{1+e^{-net_{h1}}}$$

$$net_{h1} = w_1 * i_1 + w_2 * i_2 + b_1 * 1$$

- ニューロンにおける入出力計算部分。
- 該当部分は前回スライドp.8(netやoutの計算)。
- Squashは、outputの計算で使用するシグモイド関数。

# class Neuron

```
## Determine how much the neuron's total input has to change to move closer to the expected output
##
## Now that we have the partial derivative of the error with respect to the output ( $\partial E/\partial y_i$ ) and
## the derivative of the output with respect to the total net input ( $dy_i/dz_i$ ) we can calculate
## the partial derivative of the error with respect to the total net input.
## This value is also known as the delta ( $\delta$ ) [1]
##  $\delta = \partial E/\partial z_i = \partial E/\partial y_i * dy_i/dz_i$ 
##
def calculate_pd_error_wrt_total_net_input(self, target_output):
    return self.calculate_pd_error_wrt_output(target_output) * self.calculate_pd_total_net_input_wrt_input();

## The error for each neuron is calculated by the Mean Square Error method:
def calculate_error(self, target_output):
    return 0.5 * (target_output - self.output) ** 2

## The partial derivate of the error with respect to actual output then is calculated by:
## =  $2 * 0.5 * (target\ output - actual\ output)^{(2 - 1) * -1}$ 
## =  $-(target\ output - actual\ output)$ 
##
## The Wikipedia article on backpropagation [1] simplifies to the following, but most other learning material does not [2]
## = actual output - target output
##
## Alternative, you can use (target - output), but then need to add it during backpropagation [3]
##
## Note that the actual output of the output neuron is often written as  $y_i$  and target output as  $t_i$  so:
## =  $\partial E/\partial y_i = -(t_i - y_i)$ 
def calculate_pd_error_wrt_output(self, target_output):
    return -(target_output - self.output)
```

$$E_{o1} = \frac{1}{2}(target_{o1} - out_{o1})^2 =$$

$$\frac{\partial E_{total}}{\partial out_{o1}} = -(target_{o1} - out_{o1})$$

- 誤差計算。重み更新の材料の計算。今回スライドp.8で呼び出されているもの。  
前回スライドp.15~p.19等が該当部分。

# class Neuron

```
# The total net input into the neuron is squashed using logistic function to calculate the neuron's output:  
#  $y_i = \phi = 1 / (1 + e^{-z_i})$   
# Note that where  $i$  represents the output of the neurons in whatever layer we're looking at and  $i$  represents the layer below it  
# The derivative (not partial derivative since there is only one variable) of the output then is:  
#  $dy_i/dz_i = y_i * (1 - y_i)$   
def calculate_pd_total_net_input_wrt_input(self):  
    return self.output * (1 - self.output)  
  
# The total net input is the weighted sum of all the inputs to the neuron and their respective weights.  
#  $= z_i = net_i = x_1w_1 + x_2w_2 \dots$   
# The partial derivative of the total net input with respect to a given weight (with everything else held constant) then is:  
#  $= \partial z_i / \partial w_i = \text{some constant} + 1 * x_i w_i^{(1-0)} + \text{some constant} \dots = x_i$   
def calculate_pd_total_net_input_wrt_weight(self, index):  
    return self.inputs[index]
```

$$\frac{\partial out_{o1}}{\partial net_{o1}} = out_{o1}(1 - out_{o1})$$

$$\frac{\partial net_{o1}}{\partial w_5} = 1 * out_{h1} * w_5^{(1-1)} + 0 + 0 = out_{h1}$$

- 重み更新の材料の計算。前回スライドp.20,p.21参照。

$$\varphi(z) = \frac{1}{1 + e^{-z}}$$

which has a nice derivative of:

$$\frac{\partial \varphi}{\partial z} = \varphi(1 - \varphi)$$

$$\begin{aligned} \varphi &= 1/(e^{-z} + 1) = (e^{-z} + 1)^{-1} \\ \partial\varphi/\partial z &= e^{-z}/(e^{-z} + 1)^2 \\ &= 1/(e^{-z} + 1)(e^{-z} + 1 - 1)/(e^{-z} + 1) \\ &= \varphi(1 - \varphi) \end{aligned}$$

←

# 演習

- ユニットの持つ初期値、重み、バイアス、目標値を変更して検証を行ってみる。  
誤差の変動具合等が考察できる。
- さらに、ユニット数を増やして考察してみる。

# 3年生輪読予定表改訂版

| 担当箇所 | 名前  | 発表予定日 |
|------|-----|-------|
| 1-1  | 保科  | 5/12  |
| 1-3  | 猪狩  | 5/12  |
| 2-1  | 村田  | 5/19  |
| 2-2  | 西澤  | 5/19  |
| 2-3  | 西ヶ谷 | 5/19  |
| 2-3  | 坂中  | 5/19  |
| 3-1  | 米倉  | 5/26  |
| 3-1  | 田之井 | 5/26  |
| 3-2  | 松田  | 5/26  |
| 3-2  | 清水  | 5/26  |

# 3年生輪読予定表改訂版

| 担当箇所 | 名前 | 発表予定日 |
|------|----|-------|
| 3-3  | 宿野 | 6/2   |
|      | 前原 |       |
|      | 村田 |       |
| 4章   | 門木 | 6/9   |
|      | 山下 |       |
|      | 上野 | 6/16  |
|      | 數見 |       |
| 5章   | 下窪 | 6/16  |
|      | 黒川 |       |
|      | 関根 |       |
|      | 坂本 |       |

# 次回

- 輪読(4章、5章)
- RNN?
- 2年生は、どのアルゴリズムを選択するか考えてみる。  
作成したい内容の実装上の質問も受け付けます。

